

## **FAILURE TOLERANT PARALLEL POWER SOURCE CONFIGURATION**

### **INVENTOR**

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This application claims the benefit of U.S. Provisional Application No. 60/410,392 filed September 12, 2002, which is hereby fully incorporated by reference herein as though set forth in full.

### **BACKGROUND OF THE INVENTION**

#### **1. Field of the Invention**

This invention relates generally to parallel power sources, and more specifically, to a configuration of parallel power sources capable of powering a load which is tolerant of failure of individual ones of the power sources.

#### **2. Related Art**

In electrical power systems, it is often desirable to connect power sources in parallel in order to increase the power capacity and/or failure tolerance of the system. Feedback from a load may indicate the power demand of the load. The power supplied by individual ones of the parallel combination may be adjusted in response to the demand from the load. Load balancing may be achieved by adjusting the power supplied by an individual power source according to its power capacity.

Conventional parallel configurations of power sources are susceptible to several problems. One such problem is that these configurations are subject to single point failures of the feedback path from the load back to the parallel combination. If the feedback path is severed or disrupted for any reason, the entire parallel combination shuts down. For example, in a master/slave configuration, whereby one of the power sources acts as the master and the rest are

master/slave configuration, whereby one of the power sources acts as the master and the rest are slaves, the slaves are regulated by, and therefore dependent on, the master. If the master goes down, the entire system goes down.

Another such problem is that slight variations in the individual power sources can lead to an unbalanced condition, whereby one or more of the sources may operate at or near maximum capacity while the remaining sources are idle or furnish little or no load current. If allowed to occur over a long period of time, this unbalanced condition subjects the sources under load to accelerated thermal and electrical stress.

A representative conventional parallel power source system is disclosed in U.S. Patent No. 6,157,555. In this system, a central feedback loop senses the load current delivered by the system, and mutually communicates a control signal derived from the load current to individual regulators in each of the parallel sources. In response to the control signal, each power supply regulates its output to contribute a substantially equal amount of current to the load, thereby balancing the system without having to rely on current matching to a particular master power source. However, because the individual regulators share a common control signal, this system is susceptible to single point failure in that a malfunction in the circuitry comprising the load current sensor or the central feedback loop can potentially affect the output of every source in the parallel scheme.

## SUMMARY

A system comprising a plurality of power sources coupled in parallel is described. The sources are each coupled to a first bus and to a second bus. A power sensing element corresponding to each power source is provided, and each power sensing element allows sensing of power demanded by the load from its corresponding source. Each power sensing element is coupled to a third bus. Each source is configured to sense power demanded from it by the load, and, in response thereto, supply power to the load. If one of the sensing elements fails, the other power supplies will still be able to sense load demand. In the event of a power failure of a power

source, in one embodiment, an interlock responsive to the failure condition interrupts current flow through the sensing element corresponding to the failed source, and optionally disconnects the power source from the load. The system is thus resistant to single point failures.

The parallel system may comprise identical or disparate individual power sources. In one embodiment, the system comprises a plurality of AC or DC power sources. The parallel system may also comprise individual power sources having identical or disparate power capacities. In one embodiment, one or more of the sources are fuel cells.

The power sensing elements may be coupled external to the power sources, or may be located internal to each power source. For an AC power source, the corresponding power sensing element may allow sensing of load current magnitude and phase. For a DC power source, the corresponding power sensing element may allow sensing of the magnitude of the load current. The power sensing element may comprise any suitable instrument, such as a resistor, an inductive current transducer, or a Hall effect current transducer. In one embodiment, a power sensing element comprises a resistor having a resistance inversely proportional to the power capacity of its corresponding source.

Other systems, methods, features and advantages of the invention will be or will become apparent to one with skill in the art upon examination of the following figures and detailed description. It is intended that all such additional systems, methods, features and advantages be included within this description, be within the scope of the invention, and be protected by the accompanying claims.

### **BRIEF DESCRIPTION OF THE FIGURES**

The invention can be better understood with reference to the following figures. The components in the figures are not necessarily to scale, emphasis instead being placed upon illustrating the principles of the invention. Moreover, in the figures, like reference numerals designate corresponding parts throughout the different views.

Figure 1 illustrates one embodiment of a system according to the invention.

Figure 2 illustrates an example of a system according to the invention comprising three parallel sources each configured with external resistive power sensing elements.

Figure 3 illustrates another example of a system according to the invention, wherein power sensing elements are located internal to each source.

Figure 4 is a flowchart of an embodiment of a method according to the invention for operating parallel power sources.

Figure 5 is a flowchart of an embodiment of a method according to the invention for operating and regulating the output of parallel power sources.

#### DETAILED DESCRIPTION

As utilized herein, terms such as “about” and “substantially” and “nearly” are intended to allow some leeway in mathematical exactness to account for tolerances that are acceptable in the trade. Accordingly, any deviations upward or downward from the value modified by the terms “about” or “substantially” or “approximately” in the range of 1% to 25% or less should be considered to be explicitly within the scope of the stated value.

Figure 1 illustrates an embodiment of a system 100 according to the invention. The system comprises  $n$  power sources configured electrically in parallel, wherein  $n$  is an integer of two or more. In Figure 1, the  $n$  power sources are identified as  $S_1, S_2, \dots S_n$ . The system 100 further comprises a first bus 102, a second bus 104, and a third bus 106. In system 100, each source  $S_1, S_2, \dots S_n$  is configured with a pair of output terminals having opposite polarities: a positive output terminal 108(1), 108(2),  $\dots$  108( $n$ ), and a negative output terminal 110(1), 110(2),  $\dots$  110( $n$ ). Each of the positive terminals 108(1), 108(2),  $\dots$  108( $n$ ) is coupled to first bus 102, and each of the negative terminals 110(1), 110(2),  $\dots$  110( $n$ ) is coupled to second bus 104.

The system 100 further comprises  $n$  sensing elements  $E_1, E_2, \dots E_n$ , each corresponding, respectively, to one of the power sources  $S_1, S_2, \dots S_n$ . Each sensing element is coupled to the third bus 106. In the embodiment shown, each sensing element is also coupled between the

second and third busses, but it should be appreciated that other coupling configurations are possible, such as where the sensing elements are coupled between the first and third busses. Each of the sensing elements  $E_1, E_2, \dots E_n$  is configured to allow sensing of the portion of the overall load demand to be met by the corresponding power source  $S_1, S_2, \dots S_n$ . In one embodiment, each of the elements  $E_1, E_2, \dots E_n$  is configured to allow sensing of the electrical current flow required from the corresponding power source  $S_1, S_2, \dots S_n$  by a load, and to allow derivation of respective control signals  $J_1, J_2, \dots J_n$ , at the corresponding power sources  $S_1, S_2, \dots S_n$  whereby each control signal is representative of the current flow through its corresponding power sensing element  $E_1, E_2, \dots E_n$  when the system 100 is in operation. Each source  $S_1, S_2, \dots S_n$  is configured with a means for regulating its output current responsive to the corresponding control signal  $J_1, J_2, \dots J_n$ . In one implementation, the sensing elements  $E_1, E_2, \dots E_n$  are all resistors, and the control signals  $J_1, J_2, \dots J_n$  are each derived from the common voltage drop across each of the resistors. In Figure 1, for example, assuming the sensing element  $E_1$  is a resistor having a resistance  $R$ , the voltage drop across  $E_1$  is  $V = I_1 \times R$ . The corresponding power source may derive the control signal from the common voltage drop (which may be sensed at any arbitrary location between the third bus and either of the first and second busses) and the resistance of the resistor corresponding to the power source. In one embodiment, the resistance of the resistor corresponding to a power source is stored at the power source. The power source senses the common voltage drop between the two busses, and divides it by the resistance of its corresponding resistor to arrive at an estimate of the current demanded from it by the load. The power source then derives the control signal from this estimated current.

In the embodiment illustrated in Figure 1, when the system 100 is in operation, a load 112 is coupled between first bus 102 and third bus 106, but it should be appreciated that other coupling configurations are possible, such as a configuration where the load 112 is coupled between the second bus 104 and the third bus 106. (The load 112 and its interconnections to the system 100 are shown in phantom in Figure 1 since they are distinct and separate from the system 100). The load 112 demands bulk power from system 100, without preference among any of the sources  $S_1, S_2, \dots S_n$  for a particular source of load current 114. Thus, load 112 draws an

aggregate load current 114 from sources  $S_1, S_2, \dots S_n$ , where current 114 is the aggregation of currents  $I_1, I_2, \dots I_n$  originating from each of the respective sources  $S_1, S_2, \dots S_n$ . Each individual current  $I_1, I_2, \dots, I_n$  flows through its corresponding power sensing element  $E_1, E_2, \dots, E_n$ . The contribution to the load current 114 from each of the sources  $S_1, S_2, \dots S_n$  is controlled by the current regulation means corresponding to each such source, and is determined responsive to the control signal  $J_1, J_2, \dots J_n$  corresponding to that source. As the demand for load current 114 varies up or down, each sensor  $E_1, E_2, \dots E_n$  allows sensing of the changing load condition in proportion to the amount of current contributed by its corresponding source  $S_1, S_2, \dots S_n$ . In this manner, each source in the parallel scheme regulates its output current independently, without reliance on any control signal that may be common to more than one source. Accordingly, unlike conventional systems, system 100 is not or less susceptible to single point failures.

For example, consider a scenario in which a single point failure occurs at power sensing element  $E_1$ . As a result of the failure, no current flows through element  $E_1$ , and, in response, the output of  $S_1$  reduces to zero. At the same time, the current demand on sources  $S_2, \dots S_n$  increases to compensate for the loss of the contribution from source  $S_1$ . Power sensors  $E_2, \dots E_n$  allow sensing of the increase in demand and also allow derivation of corrective control signals  $J_2, \dots J_n$  at their corresponding sources  $S_2, \dots S_n$ . Each of these sources increases its output current accordingly, thereby substantially maintaining load current 114 at the desired level when the system reaches a steady state condition. The same result holds true for a failure occurring at any other current sensing element  $E_2, \dots E_n$ .

As another example, consider a single point failure equivalent to a power failure at any one of the sources  $S_1, S_2, \dots S_n$ , such as an open circuit condition occurring at an output terminal, 108 or 110, of source  $S_1$ . Again, the result is a loss of the affected source, while the remaining sources  $S_2, \dots S_n$  respond to a demand for an increase in current contributions. However, in this type of failure scenario, in order for the remaining sources  $S_2, \dots S_n$  to increase their current output to meet the demand, it is essential that no portion of load current 114 flow through the power sensor corresponding to the failed source, which in this example is sensor  $E_1$ .

It is therefore necessary to provide an interlock (not shown) that disconnects from load path 106 (i.e. the third bus) any sensor that corresponds to a failed source. Thus, in this example, when source  $S_1$  fails, sensor  $E_1$  is disconnected and  $I_1$  goes to zero. As a result, each load current  $I_2, \dots, I_n$  increases, and accordingly, each element  $E_2, \dots, E_n$  allows derivation of a corrective control signal  $J_2, \dots, J_n$  at its corresponding power source  $S_2, \dots, S_n$ . After a brief transient condition, the system stabilizes at which point sources  $S_2, \dots, S_n$  share the load in some proportion. In this manner, the operation of system 100 remains substantially unaffected by the failure.

Each source  $S_1, S_2, \dots$  or  $S_n$  may be any device capable of generating or distributing electrical power. Examples of the power sources which are possible include AC power sources, DC power sources, generators, transformers, batteries, inverters, power supplies, solar panels, and fuel cells. In one implementation, the power sources are metal/air fuel cells, which have power capacities that change over time as fuel is consumed while delivering power to a load. For additional information on metal/air fuel cells, the reader is referred to the following patents and patent applications, which disclose a particular embodiment of a metal/air fuel cell in which the metal is zinc: U.S. Patent Nos. 5,952,117; 6,153,328; and 6,162,555; and U.S. Patent Application Nos. 09/521,392; 09/573,438; and 09/627,742, each of which is incorporated herein by reference as though set forth in full.

In one embodiment of system 100, sources  $S_1, S_2, \dots, S_n$  have identical power capacities  $P_1 = P_2 = \dots = P_n$ . In a second embodiment, two or more of the sources have different power capacities. In a third embodiment, two or more of the sources have different power capacities and each of the sensing elements  $E_1, E_2, \dots, E_n$  varies in accordance with the power capacity of the corresponding source  $S_1, S_2, \dots, S_n$ . In one implementation, the sensing elements  $E_1, E_2, \dots, E_n$  are each current sensing elements such as resistors having a resistance which is inversely proportional to the power capacity of the corresponding source. In this implementation, the ratio  $I_j : I_k$  of the contributions of load current supplied by any two sources is substantially equivalent to the ratio  $P_j : P_k$  of the power capacities of the same two sources. That is achieved because the total load current  $I_L$  will divide into branch currents  $I_1, I_2, \dots, I_n$  that flow through each corresponding sensing element  $E_1, E_2, \dots, E_n$  according to the well-known current divider rule for

current flow through parallel resistors. One skilled in the art will recognize that the inverse relationship of the resistance of each branch to the power capacity of its corresponding source will result in each branch current having a magnitude in direct proportion to its corresponding power capacity.

The sensing elements  $E_1, E_2, \dots E_n$  can be any instrument capable of allowing sensing of power demanded by the load from the corresponding power source  $S_1, S_2, \dots S_n$ . In one embodiment, the sensing elements  $E_1, E_2, \dots E_n$  are current sensing elements. Examples of current sensing elements which are possible include resistors, current transducers that allow sensing of current by means of magnetic induction, and current transducers that comprise Hall effect sensors. In one implementation, the type of sensing elements which are employed in relation to the sources  $S_1, S_2, \dots S_n$  are identical. In a second embodiment, the types of elements which are employed may vary among the individual power sources  $S_1, S_2, \dots S_n$ . Other implementations include current sensors that comprise any one of the above current sensing technologies having an impedance that is inversely proportional to the power capacity of the power source corresponding to the current sensor.

In one implementation, the power sources  $S_1, S_2, \dots S_n$  are each DC power sources, and the sensing elements  $E_1, E_2, \dots E_n$  are each configured to allow sensing of the magnitude of the current originating from the corresponding power source. In this implementation, the control signals  $J_1, J_2, \dots J_n$  are each representative of the magnitude of the current required from the corresponding power source. In a second implementation, the power sources  $S_1, S_2, \dots S_n$  are each AC power sources, and the sensing elements  $E_1, E_2, \dots E_n$  are each configured to allow sensing of the magnitude and/or the phase of the current required from the corresponding power source. In this implementation, the control signals  $J_1, J_2, \dots J_n$  are each representative of the magnitude and/or phase of the current required from the corresponding power source. In one example, each control signal is a complex value representing both the magnitude and phase of the corresponding current.



Figure 2 illustrates an example of a system 200 according to the invention comprising three parallel sources  $S_1$ ,  $S_2$ , and  $S_3$  collectively delivering a load current  $I_L$  to a load 212. Current  $I_L$  comprises the aggregation of individual currents  $I_1$ ,  $I_2$ , and  $I_3$ , originating respectively from sources  $S_1$ ,  $S_2$ , and  $S_3$ . The currents respectively flow through external sensing elements  $E_1$ ,  $E_2$ , and  $E_3$ , corresponding respectively to sources  $S_1$ ,  $S_2$  and  $S_3$ . Each element  $E_1$ ,  $E_2$ , and  $E_3$  comprises a resistor having a resistance value inversely proportional to the capacity of its corresponding source. In one configuration, a sizing standard is utilized such that the ratio of the resistances of any two sensing elements is inversely related to the ratio of the power capacities of the corresponding sources. The sizing standard should be selected to produce resistance values that are compatible with both the interfacing load circuitry and the interfacing current sensing circuitry. Thus, for example, assume the sources have capacities, or power ratings, of  $S_1 = P$ ,  $S_2 = 5P$ , and  $S_3 = 10P$ , and assume the resistive element  $E_1$  has a nominal resistance value of  $R$ . A sizing standard can then be selected to determine the proper resistance values of the resistive elements for any source in the parallel system. In this example, for a power source having a power capacity of  $nP$ , the resistance of its corresponding a resistive element is  $R/n$ , where  $n$  is any real number. The resistances of the other two sensing elements will be as follows:  $E_2 = 0.2R$ , and  $E_3 = 0.1R$ . Those skilled in the art will recognize that, under these conditions, the load current  $I_L$  will divide among the sources  $S_1$ ,  $S_2$ ,  $S_3$  in proportion to their respective capacities. In other words, the following allocation of the load current  $I_L$  will result:  $I_1 = 1/16 I_L$ ,  $I_2 = 5/16 I_L$ , and  $I_3 = 10/16 I_L$ .

One of skill in the art will appreciate, from a reading of this disclosure, that additional sources can be added to the system 200 to increase the capacity of the overall system. Assuming that each such source is configured with a corresponding resistive current sensing element having a resistance inversely proportional to the power capacity of the corresponding power source in accordance with the same sizing standard, each such source will contribute a percentage of the overall load current in direct proportion to the ratio of its capacity to the capacity of the parallel system. This results in a desirable balancing or distribution of load currents, and contributes to a situation whereby each power source operates at or near its optimal efficiency range. Problems

endemic in the prior art such as accelerated aging due to thermal and electrical overstress arising from sustained operation outside of rated limits are thereby avoided.

Figure 3 shows another example of a system 300 according to the invention. System 300 comprises two parallel connected sources,  $S_1$  and  $S_2$ , having respective positive output terminals 308(1) and 308(2), respective negative output terminals 310(1) and 310(2), and respective third output terminals 316(1) and 316(2). Note that, for simplicity, the internal power transmitting or power generating circuitry coupled to the positive and negative output terminals is not shown. Each source  $S_1$  or  $S_2$  is also configured with an internal power sensing element,  $E_1$  or  $E_2$  respectively. In this particular example, the parallel connection of sources  $S_1$  and  $S_2$  is made by coupling the positive terminals 308(1) and 308(2) to a first bus 302, and by coupling the negative terminals 310(1) and 310(2) to a second bus 304. Bus bars 324(1) and 324(2), respectively located internally to each source,  $S_1$  and  $S_2$  as the case may be, respectively couple the negative terminals 310(1) and 310(2) to the respective third terminals 316(1) and 316(2). Terminals 316(1) and 316(2) are each coupled to a third bus 306. Together, sources  $S_1$  and  $S_2$  are configured to deliver load current 314 to a load 312 connected across first bus 302 and third bus 306.

In this particular example, the load current 314 is the aggregation of individual currents  $I_1$  and  $I_2$ , contributed respectively by sources  $S_1$  and  $S_2$ . Bus bars 324(1) and 324(2) respectively conduct  $I_1$  and  $I_2$  through sensing elements  $E_1$  and  $E_2$  located internally to respective sources  $S_1$  or  $S_2$ . Elements  $E_1$  and  $E_2$  transmit control signals  $J_1$  and  $J_2$ , respectively, to internal current regulator circuits 318(1) and 318(2), which may be any type of current regulation circuit known in the art and suitable for the purpose of regulating the output current  $I_1$  or  $I_2$  by means of feedback control to achieve a desired transfer characteristic. Each bus bar 324(1) or 324(2) is configured with an interlock, 326(1) or 326(2), which may be any conventional electrical and/or mechanical interlock capable of interrupting current flow by opening an electrical circuit responsive to a condition occurring in another circuit location. For example, in this embodiment, interlock 326(1) or 326(2), in response to a power failure (i.e. a loss of power output) of its corresponding source, opens its corresponding bus bar 324(1) or 324(2). Interlock 326(1) or

326(2) thereby ensures that no portion of load current 314 will flow from third bus 306 through a sensor,  $E_1$  or  $E_2$ , when power output from its corresponding power source,  $S_1$  or  $S_2$ , becomes unavailable. By way of example only, each interlock 326(1) and 326(2) is shown in Figure 3 configured as a circuit breaker (or equivalent circuit breaking device) located on its corresponding bus bar 324(1) or 324(2). However, one skilled in the art will recognize that the location and configuration of an interlock 324(1) and 324(2) may vary, provided that the interlock interrupts current flow through its corresponding current sensor,  $E_1$  or  $E_2$ , responsive to a loss of power output from source  $S_1$  or  $S_2$ . In addition, an interlock 324(1) or 324(2) may optionally comprise a second circuit breaking device (not shown) that is configured to disconnect its corresponding power source,  $S_1$  or  $S_2$ , from load 312 responsive to the same loss of power condition.

The configuration of the particular example of the system 300 shown in Figure 3 provides several practical advantages. First, because the sensing elements are located internally to the corresponding power sources, the current sensing function may be performed within a controlled and shielded environment, thereby reducing errors introduced by thermal, electrical, or magnetic interference. Second, the configuration permits a modular construction for sources  $S_1$  and  $S_2$ . A modular construction is beneficial because it allows for rapid and cost-effective manufacture and incorporation into existing dual-bus distribution schemes. Third, internal location of the sensing element facilitates the inclusion of an electrical and/or mechanical interlock that is necessary for disconnecting the current sensing element from the bus in the event of a loss of power output. For these reasons, parallel power sources of modular construction having internal current sensing elements comprise a preferred embodiment of a system according to the invention.

Figure 4 is a flowchart of an embodiment of a method 400 according to the invention of delivering power to a load from a parallel configuration of power sources. Step 402 is a sensing step, wherein power demanded by a load is individually sensed at each of a plurality of power sources that are connected electrically in parallel. As discussed previously in relation to the system embodiments of the invention, the plurality of power sources may each comprise AC sources, or they may each comprise DC sources; and the power sources may have identical power

capacity ratings, or two or more of the power sources may have different power capacity ratings. The sensing may be accomplished by any suitable means, such as those discussed previously in relation to the system embodiments of the invention. Next, a contributing step is performed in step 404. In this step, the plurality of power sources each individually contribute power in response to the power demand of the load as individually sensed in step 402. Optionally, step 406 is also performed concurrently with step 404. In step 406, the power individually provided by each source in step 404 is provided in proportion to the power capacity of the source. One of skill in the art will appreciate from a reading of this disclosure that the steps illustrated in Figure 4 may be performed in orders different from that illustrated in Figure 4. For example, it is possible for one or more of these steps to be performed simultaneously, concurrently or in parallel.

Figure 5 is a flowchart of an example of a method 500 according to the invention of delivering current to a load from a plurality of power sources coupled in parallel to first and second busses. The method begins with step 504. In step 504, the method comprises individually sensing current demanded by a load from each of the power sources. This sensing is enabled by means of a current sensing element corresponding to each of the power sources and coupled to a third bus. As discussed previously in relation to the system embodiments, in the case in which the power sources are DC power sources, sensing step 504 may comprise individually sensing the magnitude of the current demanded from each of the power sources. In the case in which the power sources are AC power sources, sensing step 504 may comprise individually sensing the magnitude and/or phase of the current demanded from each of the power sources. Step 506 follows step 504. In step 506, one or more control signals corresponding to each of the power sources are derived from the current demanded by the load from the power source as sensed in the previous step. Step 508 follows step 506. Step 508 comprises individually contributing current from each of the power sources responsive to a control signal corresponding to each source. One of skill in the art will appreciate from a reading of this disclosure that the steps illustrated in Figure 5 may be performed in orders other than those

illustrated in Figure 5. For example, it is possible for one or more of these steps to be performed simultaneously, concurrently, or in parallel.

While various embodiments of the invention have been described, it will be apparent to those of ordinary skill in the art that many more embodiments and implementations are possible that are within the scope of this invention. Accordingly, the invention is not to be restricted except in light of the attached claims and their equivalents.